

# Testing Multivariate Linear Regression with Univariate OPLS Estimators

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## Abstract

A useful *multivariate linear regression model* is  $\mathbf{y}_i = \mathbf{B}^T \mathbf{x}_i + \boldsymbol{\epsilon}_i$  for  $i = 1, \dots, n$ . The model has  $m \geq 2$  response variables  $Y_1, \dots, Y_m$  and  $p$  predictor variables  $x_1, x_2, \dots, x_p$ . One technique is to fit the  $m$  univariate multiple linear regressions of  $Y_j$  on the predictors  $\mathbf{x}$  to get  $\hat{\mathbf{B}}_U = [\hat{\boldsymbol{\beta}}_1 \hat{\boldsymbol{\beta}}_2 \cdots \hat{\boldsymbol{\beta}}_m]$ . Testing is considered for the estimators  $\hat{\mathbf{B}}_U$  that use the one component partial least squares estimators and marginal maximum likelihood estimators, including some high dimensional tests.

**KEY WORDS:** Lasso, MMLE, OLS, OPLS, Ridge Regression.

## 1 INTRODUCTION

A useful *multivariate linear regression model* is  $\mathbf{y}_i = \mathbf{B}^T \mathbf{x}_i + \boldsymbol{\epsilon}_i$  for  $i = 1, \dots, n$ . The model has  $m \geq 2$  response variables  $Y_1, \dots, Y_m$  and  $p$  predictor variables  $x_1, x_2, \dots, x_p$ . The  $\boldsymbol{\epsilon}_i$  are assumed to be independent and identically distributed (iid). The  $i$ th case is  $(\mathbf{x}_i^T, \mathbf{y}_i^T) = (x_{i1}, x_{i2}, \dots, x_{ip}, Y_{i1}, \dots, Y_{im})$ , where the constant  $x_{i1} = 1$ . The model is written in matrix form as  $\mathbf{Z} = \mathbf{X}\mathbf{B} + \mathbf{E}$  where the matrices are defined below. The model has  $E(\boldsymbol{\epsilon}_k) = \mathbf{0}$  and  $\text{Cov}(\boldsymbol{\epsilon}_k) = \boldsymbol{\Sigma}\boldsymbol{\epsilon} = (\sigma_{ij})$  for  $k = 1, \dots, n$ . Also  $E(\mathbf{e}_i) = \mathbf{0}$  while  $\text{Cov}(\mathbf{e}_i, \mathbf{e}_j) = \sigma_{ij}\mathbf{I}_n$  for  $i, j = 1, \dots, m$  where  $\mathbf{I}_n$  is the  $n \times n$  identity matrix and  $\mathbf{e}_i$  is defined below. Then the  $p \times m$  coefficient matrix  $\mathbf{B} = [\boldsymbol{\beta}_1 \boldsymbol{\beta}_2 \cdots \boldsymbol{\beta}_m]$  and the  $m \times m$  covariance matrix  $\boldsymbol{\Sigma}\boldsymbol{\epsilon}$  are to be estimated, and  $E(\mathbf{Z}) = \mathbf{X}\mathbf{B}$  while  $E(Y_{ij}) = \mathbf{x}_i^T \boldsymbol{\beta}_j$ .

The  $n \times m$  matrix of response variables and  $n \times m$  matrix of errors are

$$\mathbf{Z} = \begin{bmatrix} \mathbf{Y}_1 & \mathbf{Y}_2 & \cdots & \mathbf{Y}_m \end{bmatrix} = \begin{bmatrix} \mathbf{y}_1^T \\ \vdots \\ \mathbf{y}_n^T \end{bmatrix} \quad \text{and} \quad \mathbf{E} = \begin{bmatrix} \mathbf{e}_1 & \mathbf{e}_2 & \cdots & \mathbf{e}_m \end{bmatrix} = \begin{bmatrix} \boldsymbol{\epsilon}_1^T \\ \vdots \\ \boldsymbol{\epsilon}_n^T \end{bmatrix},$$

while the  $n \times p$  design matrix of predictor variables is  $\mathbf{X}$ .

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Least squares is the classical method for fitting the multivariate linear model. The *least squares estimators* are  $\hat{\mathbf{B}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Z} = \begin{bmatrix} \hat{\beta}_1 & \hat{\beta}_2 & \dots & \hat{\beta}_m \end{bmatrix}$ . The matrix of *predicted values* or *fitted values*  $\hat{\mathbf{Z}} = \mathbf{X} \hat{\mathbf{B}} = \begin{bmatrix} \hat{Y}_1 & \hat{Y}_2 & \dots & \hat{Y}_m \end{bmatrix}$ . The matrix of *residuals*  $\hat{\mathbf{E}} = \mathbf{Z} - \hat{\mathbf{Z}} = \mathbf{Z} - \mathbf{X} \hat{\mathbf{B}} = \begin{bmatrix} \mathbf{r}_1 & \mathbf{r}_2 & \dots & \mathbf{r}_m \end{bmatrix}$ . These quantities can be found from the  $m$  multiple linear regressions of  $Y_j$  on the predictors:  $\hat{\beta}_j = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}_j$ ,  $\hat{Y}_j = \mathbf{X} \hat{\beta}_j$  and  $\mathbf{r}_j = \mathbf{Y}_j - \hat{Y}_j$  for  $j = 1, \dots, m$ . Hence  $\hat{\epsilon}_{i,j} = Y_{i,j} - \hat{Y}_{i,j}$  where  $\hat{Y}_j = (\hat{Y}_{1,j}, \dots, \hat{Y}_{n,j})^T$ . Finally,

$$\hat{\Sigma}_{\epsilon} = \frac{(\mathbf{Z} - \hat{\mathbf{Z}})^T (\mathbf{Z} - \hat{\mathbf{Z}})}{n - p} = \frac{(\mathbf{Z} - \mathbf{X} \hat{\mathbf{B}})^T (\mathbf{Z} - \mathbf{X} \hat{\mathbf{B}})}{n - p} = \frac{\hat{\mathbf{E}}^T \hat{\mathbf{E}}}{n - p} = \frac{1}{n - p} \sum_{i=1}^n \hat{\epsilon}_i \hat{\epsilon}_i^T.$$

There are many other estimators. One technique is to fit the  $m$  univariate multiple linear regressions of  $Y_j$  on the predictors  $\mathbf{x}$  to get  $\hat{\mathbf{B}}_U = [\hat{\beta}_1 \hat{\beta}_2 \dots \hat{\beta}_m]$ . A second technique is to let  $W_{ij} = \hat{\eta}_{ij}^T \mathbf{x}$  for  $i = 1, \dots, m$  and  $j = 1, \dots, k$ . This results in  $mk$  predictors. Perform the OLS multivariate linear regression of  $Y_1, \dots, Y_m$  on  $W_{11}, \dots, W_{mk}$  to get  $\hat{\mathbf{B}}_M = [\hat{\beta}_1 \hat{\beta}_2 \dots \hat{\beta}_m]$ .

## 1.1 Multiple Linear Regression Estimators

One multiple linear regression model is

$$Y_i = \beta_1 + x_{i,2}\beta_2 + \dots + x_{i,p}\beta_p + e_i = \mathbf{x}_i^T \boldsymbol{\beta} + e_i \quad (1)$$

for  $i = 1, \dots, n$ . Here  $n$  is the sample size and the random variable  $e_i$  is the  $i$ th error. Assume that the  $e_i$  are independent and identically distributed (iid) with expected value  $E(e_i) = 0$  and variance  $V(e_i) = \sigma^2$ . In matrix notation, these  $n$  equations become  $\mathbf{Y} = \mathbf{X} \boldsymbol{\beta} + \mathbf{e}$  where  $\mathbf{Y}$  is an  $n \times 1$  vector of dependent variables,  $\mathbf{X}$  is an  $n \times p$  matrix of predictors,  $\boldsymbol{\beta}$  is a  $p \times 1$  vector of unknown coefficients, and  $\mathbf{e}$  is an  $n \times 1$  vector of unknown errors.

Let the second multiple linear regression model be  $Y|\mathbf{x}^T \boldsymbol{\beta} = \alpha + \mathbf{x}^T \boldsymbol{\beta} + e$  or  $Y_i = \alpha + \mathbf{x}_i^T \boldsymbol{\beta} + e_i$  or

$$Y_i = \alpha + x_{i,1}\beta_1 + \dots + x_{i,p}\beta_p + e_i = \alpha + \mathbf{x}_i^T \boldsymbol{\beta} + e_i \quad (2)$$

for  $i = 1, \dots, n$ . Let the  $e_i$  be as for model (1). In matrix form, this model is

$$\mathbf{Y} = \mathbf{X} \boldsymbol{\phi} + \mathbf{e}, \quad (3)$$

$\mathbf{X}$  is an  $n \times (p + 1)$  matrix with  $i$ th row  $(1, \mathbf{x}_i^T)$ ,  $\boldsymbol{\phi} = (\alpha, \boldsymbol{\beta}^T)^T$  is a  $(p + 1) \times 1$  vector, and  $\mathbf{e}$  is an  $n \times 1$  vector of unknown errors. Also  $E(\mathbf{e}) = \mathbf{0}$  and  $\text{Cov}(\mathbf{e}) = \sigma^2 \mathbf{I}_n$  where  $\mathbf{I}_n$  is the  $n \times n$  identity matrix.

For estimation with ordinary least squares, let the covariance matrix of  $\mathbf{x}$  be  $\text{Cov}(\mathbf{x}) = \boldsymbol{\Sigma}_{\mathbf{x}} = E[(\mathbf{x} - E(\mathbf{x}))(\mathbf{x} - E(\mathbf{x}))^T] = E(\mathbf{x} \mathbf{x}^T) - E(\mathbf{x})E(\mathbf{x}^T)$  and  $\boldsymbol{\eta} = \text{Cov}(\mathbf{x}, Y) = \boldsymbol{\Sigma}_{\mathbf{x}Y} = E[(\mathbf{x} - E(\mathbf{x}))(Y - E(Y))] = E(\mathbf{x}Y) - E(\mathbf{x})E(Y) = E[(\mathbf{x} - E(\mathbf{x}))Y] = E[\mathbf{x}(Y - E(Y))]$ . Let

$$\hat{\boldsymbol{\eta}} = \hat{\boldsymbol{\eta}}_n = \hat{\boldsymbol{\Sigma}}_{\mathbf{x}Y} = \mathbf{S}_{\mathbf{x}Y} = \frac{1}{n - 1} \sum_{i=1}^n (\mathbf{x}_i - \bar{\mathbf{x}})(Y_i - \bar{Y})$$

and

$$\tilde{\boldsymbol{\eta}} = \tilde{\boldsymbol{\eta}}_n = \tilde{\boldsymbol{\Sigma}} \mathbf{x}_Y = \frac{1}{n} \sum_{i=1}^n (\mathbf{x}_i - \bar{\mathbf{x}})(Y_i - \bar{Y}).$$

Then the OLS estimators for model (3) are  $\hat{\boldsymbol{\phi}}_{OLS} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$ ,  $\hat{\alpha}_{OLS} = \bar{Y} - \hat{\boldsymbol{\beta}}_{OLS}^T \bar{\mathbf{x}}$ , and

$$\hat{\boldsymbol{\beta}}_{OLS} = \tilde{\boldsymbol{\Sigma}}^{-1} \tilde{\boldsymbol{\Sigma}} \mathbf{x}_Y = \hat{\boldsymbol{\Sigma}}^{-1} \hat{\boldsymbol{\Sigma}} \mathbf{x}_Y = \hat{\boldsymbol{\Sigma}}^{-1} \hat{\boldsymbol{\eta}}.$$

For a multiple linear regression model with independent, identically distributed (iid) cases,  $\hat{\boldsymbol{\beta}}_{OLS}$  is a consistent estimator of  $\boldsymbol{\beta}_{OLS} = \boldsymbol{\Sigma}_x^{-1} \boldsymbol{\Sigma}_{\mathbf{x}Y}$  under mild regularity conditions, while  $\hat{\alpha}_{OLS}$  is a consistent estimator of  $E(Y) - \boldsymbol{\beta}_{OLS}^T E(\mathbf{x})$ .

Cook, Helland, and Su (2013) showed that the one component partial least squares (OPLS) estimator  $\hat{\boldsymbol{\beta}}_{OPLS} = \hat{\lambda} \hat{\boldsymbol{\Sigma}} \mathbf{x}_Y$  estimates  $\lambda \boldsymbol{\Sigma}_{\mathbf{x}Y} = \boldsymbol{\beta}_{OPLS}$  where

$$\lambda = \frac{\boldsymbol{\Sigma}_{\mathbf{x}Y}^T \boldsymbol{\Sigma}_{\mathbf{x}Y}}{\boldsymbol{\Sigma}_{\mathbf{x}Y}^T \boldsymbol{\Sigma}_x \boldsymbol{\Sigma}_{\mathbf{x}Y}} \quad \text{and} \quad \hat{\lambda} = \frac{\hat{\boldsymbol{\Sigma}}_{\mathbf{x}Y}^T \hat{\boldsymbol{\Sigma}} \mathbf{x}_Y}{\hat{\boldsymbol{\Sigma}}_{\mathbf{x}Y}^T \hat{\boldsymbol{\Sigma}}_x \hat{\boldsymbol{\Sigma}} \mathbf{x}_Y} \quad (4)$$

for  $\boldsymbol{\Sigma}_{\mathbf{x}Y} \neq \mathbf{0}$ . If  $\boldsymbol{\Sigma}_{\mathbf{x}Y} = \mathbf{0}$ , then  $\boldsymbol{\beta}_{OPLS} = \mathbf{0}$ . Also see Basa, Cook, Forzani, and Marcos (2024), Cook and Forzani (2024), and Wold (1975). Olive and Zhang (2024) derived the large sample theory for  $\hat{\boldsymbol{\eta}}_{OPLS} = \hat{\boldsymbol{\Sigma}} \mathbf{x}_Y$  and OPLS under milder regularity conditions than those in the previous literature, where  $\boldsymbol{\eta}_{OPLS} = \boldsymbol{\Sigma}_{\mathbf{x}Y}$ . The OPLS estimator is computed from the OLS simple linear regression of  $Y$  on  $W = \hat{\boldsymbol{\Sigma}}_{\mathbf{x}Y}^T \mathbf{x}$ , giving  $\hat{Y} = \hat{\alpha}_{OPLS} + \hat{\lambda} W = \hat{\alpha}_{OPLS} + \hat{\boldsymbol{\beta}}_{OPLS}^T \mathbf{x}$ .

The marginal maximum likelihood estimator (MMLE or marginal least squares estimator) is due to Fan and Lv (2008) and Fan and Song (2010). This estimator computes the marginal regression of  $Y$  on  $x_i$  resulting in the estimator  $(\hat{\alpha}_{i,M}, \hat{\beta}_{i,M})$  for  $i = 1, \dots, p$ . Then  $\hat{\boldsymbol{\beta}}_{MMLE} = (\hat{\beta}_{1,M}, \dots, \hat{\beta}_{p,M})^T$ . For multiple linear regression, the marginal estimators are the simple linear regression (SLR) estimators, and  $(\hat{\alpha}_{i,M}, \hat{\beta}_{i,M}) = (\hat{\alpha}_{i,SLR}, \hat{\beta}_{i,SLR})$ . Hence

$$\hat{\boldsymbol{\beta}}_{MMLE} = [\text{diag}(\hat{\boldsymbol{\Sigma}}_x)]^{-1} \hat{\boldsymbol{\Sigma}} \mathbf{x}_Y. \quad (5)$$

If the  $\mathbf{t}_i$  are the predictors that are scaled or standardized to have unit sample variances, then

$$\hat{\boldsymbol{\beta}}_{MMLE} = \hat{\boldsymbol{\beta}}_{MMLE}(\mathbf{t}, Y) = \hat{\boldsymbol{\Sigma}}_{\mathbf{t}Y} = \mathbf{I}^{-1} \hat{\boldsymbol{\Sigma}}_{\mathbf{t}Y} = \hat{\boldsymbol{\eta}}_{OPLS}(\mathbf{t}, Y) \quad (6)$$

where  $(\mathbf{t}, Y)$  denotes that  $Y$  was regressed on  $\mathbf{t}$ , and  $\mathbf{I}$  is the  $p \times p$  identity matrix.

High dimensional regression has  $n/p$  small. A fitted or population regression model is sparse if  $a$  of the predictors are active (have nonzero  $\hat{\beta}_i$  or  $\beta_i$ ) where  $n \geq Ja$  with  $J \geq 10$ . Otherwise the model is nonsparse. A high dimensional population regression model is abundant or dense if the regression information is spread out among the  $p$  predictors (nearly all of the predictors are active). Hence an abundant model is a nonsparse model.

The Tibshirani (1996) lasso estimator and Hoerl and Kennard (1970) ridge regression estimator are also interesting. The  $k$  component partial least squares (PLS) estimator  $\hat{\boldsymbol{\beta}}_{kPLS}$  can be found from the OLS regression of  $Y$  on  $W_1, \dots, W_k$  where  $W_i = \hat{\boldsymbol{\Sigma}}_{\mathbf{x}Y}^T \hat{\boldsymbol{\Sigma}}_x^{i-1} \mathbf{x} = \hat{\boldsymbol{\eta}}_i^T \mathbf{x}$  with  $\hat{\boldsymbol{\eta}}_i = \hat{\boldsymbol{\Sigma}}_x^{i-1} \hat{\boldsymbol{\Sigma}}_{\mathbf{x}Y}$ .

Olive and Zhang (2024) proved that there are often many valid population models for multiple linear regression, gave theory for  $\hat{\Sigma}_{\mathbf{x}Y}$  and OPLS, and gave some theory for the MMLE for multiple linear regression under the constant variance assumption. Olive et al. (2024) gave more theory for the MMLE.

## 1.2 More Multivariate Estimators

Let the first multivariate linear regression model be

$$\mathbf{Z} = \mathbf{X}\mathbf{B} + \mathbf{E}. \quad (7)$$

Let the second multivariate linear regression model be

$$\mathbf{Z} = \boldsymbol{\alpha} + \mathbf{X}\mathbf{B} + \mathbf{E} \quad (8)$$

where  $\boldsymbol{\alpha}$  is the  $n \times m$  matrix of constants with  $i$ th row equal to the vector of constants  $(\alpha_1, \dots, \alpha_m)^T$ . Use the second model for the following three estimators.

Then

$$\hat{\mathbf{B}}_{MMLE} = [\text{diag}(\hat{\Sigma}_{\mathbf{x}})]^{-1} \hat{\Sigma}_{\mathbf{x}, \mathbf{y}}.$$

The MMLE tends to estimate  $p\mathbf{Y}_i$  for  $i = 1, \dots, m$ .

The multivariate estimator obtained from the univariate OPLS regressions is

$$\hat{\mathbf{B}}_{UOPLS} = [\hat{\boldsymbol{\beta}}_1 \ \hat{\boldsymbol{\beta}}_2 \ \cdots \ \hat{\boldsymbol{\beta}}_m] = [\hat{\lambda}_1 \hat{\Sigma}_{\mathbf{x}Y_1}, \dots, \hat{\lambda}_m \hat{\Sigma}_{\mathbf{x}Y_m}]. \quad (9)$$

There are PLS estimators  $\hat{\mathbf{B}}_{PLS}$  for multivariate linear regression. Obtain the  $mk$  predictors  $W_{ij} = \hat{\Sigma}_{\mathbf{x}}^{-1} \hat{\Sigma}_{\mathbf{x}Y_i}^T \mathbf{x}$  for  $i = 1, \dots, m$  and  $j = 1, \dots, k$ . Then perform the OLS multivariate linear regression of  $Y_1, \dots, Y_m$  on the  $W_{ij}$  to get  $\hat{\mathbf{B}}_{MkPLS} = [\hat{\boldsymbol{\beta}}_1, \dots, \hat{\boldsymbol{\beta}}_m]$  which is not the PLS estimator.

## 2 Large Sample Theory

For the following theorem, consider a subset of  $k$  distinct elements from  $\tilde{\Sigma}$  or from  $\hat{\Sigma}$ . Stack the elements into a vector, and let each vector have the same ordering. For example, the largest subset of distinct elements corresponds to

$$\text{vech}(\tilde{\Sigma}) = (\tilde{\sigma}_{11}, \dots, \tilde{\sigma}_{1p}, \tilde{\sigma}_{22}, \dots, \tilde{\sigma}_{2p}, \dots, \tilde{\sigma}_{p-1,p-1}, \tilde{\sigma}_{p-1,p}, \tilde{\sigma}_{pp})^T = [\tilde{\sigma}_{jk}].$$

For random variables  $x_1, \dots, x_p$ , use notation such as  $\bar{x}_j =$  the sample mean of the  $x_j$ ,  $\mu_j = E(x_j)$ , and  $\sigma_{jk} = \text{Cov}(x_j, x_k)$ . Let

$$n \text{vech}(\tilde{\Sigma}) = [n \tilde{\sigma}_{jk}] = \sum_{i=1}^n [(x_{ij} - \bar{x}_j)(x_{ik} - \bar{x}_k)].$$

For general vectors of elements, the ordering of the vectors will all be the same and be denoted vectors such as  $\tilde{\mathbf{c}} = [\tilde{\sigma}_{jk}]$ ,  $\mathbf{c} = [\sigma_{jk}]$ ,  $\mathbf{z}_i = [(x_{ij} - \bar{x}_j)(x_{ik} - \bar{x}_k)]$ , and

$\mathbf{w}_i = [(x_{ij} - \mu_j)(x_{ik} - \mu_k)]$ . Let  $\bar{\mathbf{w}}_n = \sum_{i=1}^n \mathbf{w}_i/n$  be the sample mean of the  $\mathbf{w}_i$ . Assuming that  $Cov(\mathbf{w}_i) = \Sigma_{\mathbf{w}}$  exists, then  $E(\mathbf{w}_i) = E(\bar{\mathbf{w}}_n) = \mathbf{c}$ .

The following Olive et al. (2024) theorem proves that sample covariance matrices are asymptotically normal. We use  $Cov(\mathbf{w}_i) = \Sigma_{\mathbf{d}}$  to avoid confusion with the  $\Sigma_{\mathbf{w}}$  used in OPLS theory.

**Theorem 1.** Assume the cases  $\mathbf{x}_i$  are iid and that  $Cov(\mathbf{w}_i) = \Sigma_{\mathbf{d}}$  exists. Using the above notation with  $\mathbf{c}$  a  $k \times 1$  vector,

- i)  $\sqrt{n}(\hat{\mathbf{c}} - \mathbf{c}) \xrightarrow{D} N_k(\mathbf{0}, \Sigma_{\mathbf{d}})$ .
- ii)  $\sqrt{n}(\hat{\mathbf{c}} - \mathbf{c}) \xrightarrow{D} N_k(\mathbf{0}, \Sigma_{\mathbf{d}})$ .
- iii)  $\hat{\Sigma}_{\mathbf{d}} = \hat{\Sigma}_{\mathbf{z}} + O_P(n^{-1/2})$  and  $\tilde{\Sigma}_{\mathbf{d}} = \tilde{\Sigma}_{\mathbf{z}} + O_P(n^{-1/2})$ .

### 3 Testing

Consider model (8) with iid cases where  $\mathbf{d}$  is a vector of distinct elements of  $\mathbf{B} = \mathbf{B}_{MMLE}$  or  $\mathbf{B} = \mathbf{B}_{UOPLS}$ . Then  $H_0 : \mathbf{d} = \mathbf{0}$  is true iff  $H_0 : \mathbf{c} = \mathbf{0}$  is true where the  $c_{ij}$  are the covariances corresponding to the  $d_{ij}$ . As an illustration, some of important tests are whether a subset of rows of  $\mathbf{B}$  are equal to  $\mathbf{0}$ . See Olive, Pelawa Watagoda, and Rupasinghe Arachchige Don (2015). Let the  $i$ th row of  $\mathbf{B}$  in model (8) be  $\mathbf{b}_i = (\beta_{i1}, \dots, \beta_{im})$ . Consider  $\hat{\mathbf{B}}_{UOPLS}$  where  $\lambda_i \neq 0$  for  $i = 1, \dots, m$ . Testing  $H_0 : \mathbf{b}_i^T = \mathbf{0}$  is equivalent to testing  $H_0 : (\text{Cov}(x_i Y_1), \dots, \text{Cov}(x_i Y_m))^T = \Sigma_{x_i} \mathbf{y} = \mathbf{0}$ . Under iid cases, this test is similar to testing  $\Sigma_{\mathbf{x}Y} = \mathbf{0}$  with the  $\mathbf{x}$  replaced by  $\mathbf{y}$  and  $Y$  replaced by  $x_i$ . Tests for rows  $i_1, i_2, \dots, i_k$  use  $H_0 : (\mathbf{b}_{i_1}, \dots, \mathbf{b}_{i_k})^T = \mathbf{0}$ , and are similar. If  $m$  and  $K$  are small, high dimensional tests can be done.

If  $m$  is small, rows of  $\mathbf{B}_{UOPLS}$  can be tested. If  $p$  is small, columns of  $\mathbf{B}_{UOPLS}$  can be tested. If both  $p$  and  $m$  are large,  $\mathbf{B}_{ij}$  can be tested.

## 4 EXAMPLES AND SIMULATIONS

## 5 CONCLUSIONS

There are many multivariate linear regression estimators, including envelope estimators and partial least squares. See, for example, Cook (2018), Cook and Forzani (2024), Cook and Su (2013), Cook, Helland, and Su (2013), and Su and Cook (2012). Univariate methods like ridge regression and lasso can also be extended to multivariate linear regression. See, for example, Obozinski, Wainwright, and Jordan (2011).

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