Math 480 Exam 2 is Wed. Nov. 2. You are allowed 11 sheets of notes and a calculator. The exam emphasizes HW5-8, and Q5-8.

From the 1st exam:

The conditional probability of A given B is $P(A|B) = \frac{P(A \cap B)}{P(B)}$ if P(B) > 0.

Complement rule. $P(A) = 1 - P(\overline{A}).$

Know P(Y was at least k) = $P(Y \ge k)$ and P(Y at most k) = $P(Y \le k)$.

The variance of Y is $V(Y) = E[(Y - E(Y))^2]$ and the standard deviation of Y is $SD(Y) = \sigma = \sqrt{V(Y)}$. Short cut formula for variance. $V(Y) = E(Y^2) - (E(Y))^2$

If
$$S_Y = \{y_1, y_2, ..., y_k\}$$
 then $E(Y) = \sum_{i=1}^k y_i p(y_i) = y_1 p(y_1) + y_2 p(y_2) + \dots + y_k p(y_k)$

and
$$E[g(y)] = \sum_{i=1}^{k} g(y_i) p(y_i) = g(y_1) p(y_1) + g(y_2) p(y_2) + \dots + g(y_k) p(y_k)$$
. Also $V(Y) = \sum_{i=1}^{k} g(y_i) p(y_i) = g(y_1) p(y_1) + g(y_2) p(y_2) + \dots + g(y_k) p(y_k)$.

$$\sum_{i=1}^{n} (y_i - E(Y))^2 p(y_i) = (y_1 - E(Y))^2 p(y_1) + (y_2 - E(Y))^2 p(y_2) + \dots + (y_k - E(Y))^2 p(y_k).$$

Often using $V(Y) = E(Y^2) - (E(Y))^2$ is simpler where $E(Y^2) = y_1^2 p(y_1) + y_2^2 p(y_2) + \dots + y_k^2 p(y_k)$. $E(c) = c, \ E(cg(Y)) = cE(g(Y)), \text{ and } E[\sum_{i=1}^k g_i(Y)] = \sum_{i=1}^k E[g_i(Y)] \text{ where } c \text{ is any}$

constant.

If Y has pdf f(y), then $\int_{-\infty}^{\infty} f(y)dy = 1$, $F(y) = \int_{-\infty}^{y} f(t)dt$ and f(y) = F'(y) except at possibly countably many points, $E[g(Y)] = \int_{-\infty}^{\infty} g(y)f(y)dy$, $P(a < Y < b) = F(b) - F(a) = \int_{a}^{b} f(y)dy$ where < can be replaced by \leq .

 $F(y) = P(Y \le y)$. If Y has a pmf, $P(a < Y \le b) = F(b) - F(a)$.

MATERIAL "NOT ON 1st EXAM"

22) Know how to use most of the RVs from the first page of the exam 1 review. (The Poisson, Binomial, and Weibull are less likely.)

23) The support of RV Y is the set $\{y : f(y) > 0\}$ or $\{y : p(y) > 0\}$. Formulas for F(y), f(y), and p(y) are often given for the support or for the support plus the boundaries of the support (often for $(-\infty, b], [a, b]$ or $[a, \infty)$).

Suppose that Y is a RV and that $E(Y) = \mu$ and standard deviation $\sqrt{V(Y)} = SD(Y) = \sigma$ exist. Then the **z-score** is $Z = \frac{Y - \mu}{\sigma}$. Note that E(Z) = 0, and V(Z) = 1.

24) Know how to do a **forwards calculation using the** Z **table** where $Z \sim N(0, 1)$. In the story problem you will be told that X is approximately normal with some mean and SD(X) or V(X). You will be given one or two x^* values and asked **to find a probability** or proportion. Draw a line and mark down the mean and the x^* values. Standardize with $z^* = (x^* - \mu)/\sigma$, and sketch a Z curve (N(0,1) pdf). Show how the Z table is used. Then $P(X \leq x^*) = P(Z \leq z^*)$, $P(X > x^*) = 1 - P(Z \leq z^*)$ and $P(x_1^* < X < x_2^*) = P(Z \leq z_2^*) - P(Z \leq z_1^*)$. Note that < can be replaced by \leq . Given a z^* , use the leftmost column and top row of the Z table. Intersect this row and column to get a 4 digit decimal = $P(Z \leq z^*)$. Note that $P(Z > 3.5) \approx 0 \approx P(Z < -3.5)$ and $P(Z < 3.5) \approx 1 \approx P(Z > -3.5)$. Also, P(Z > z) = P(Z < -z). The normal pdf is symmetric about μ so the N(0,1) pdf is symmetric about 0 and bell shaped. See HW5 and Q5.

25) Know how to do a **backwards calculation using the** Z **table.** Here you are given a probability and asked to find one or two x^* values, often a percentile x_p where $P(X \leq x_p) = p$ if $X \sim N(\mu, \sigma^2)$. The Z table gives areas to the left of z^* . So if you are asked to find the top 5%, that is the same as finding the bottom 95%. If you are asked to find the bottom 25%, the Z table gives the correct value. If you are asked to find the two values containing the middle 95%, then 5% of the area is outside of the middle. Hence .025 area is to the left of $x^*(lo)$ and .025 + .95 = .975 area is to the left of $x^*(hi)$. The area to the left of x^* , is also the area to the left of z^* . Find the largest 4 digit number smaller than the desired area and the smallest 4 digit number larger than the desired area. These two numbers will be found in the middle of the Z table. Take the number closest to the desired area, and to find the corresponding z^* , examine the row and column containing the number. If there is a tie, average the two numbers to get z^* . Go along the row to the entry in the leftmost column of the Z table and go along the column to the top row of the Z table. For example, if your 4 digit number is .9750, $z^* = 1.96$. To get the corresponding x^* , use $x^* = \mu + \sigma z^*$. The 5th percentile has $z^* = -1.645$ and the 95th percentile has $z^* = 1.645$ because there is a tie. See HW5, Q5. Let Y_1 and Y_2 be discrete random variables. Then the **joint probability mass**

function $p(y_1, y_2) = P(Y_1 = y_1, Y_2 = y_2)$ and is often given by a table.

The function $p(y_1, y_2)$ is a joint pmf if $p(y_1, y_2) \ge 0, \forall y_1, y_2$ and if

$$\sum \qquad p(y_1, y_2) = 1.$$

 $(y_1, y_2): p(y_1, y_2) > 0$

The **joint cdf** of any two random variables Y_1 and Y_2 is $F(y_1, y_2) = P(Y_1 \le y_1, Y_2 \le y_2), \forall y_1, y_2.$

Let Y_1 and Y_2 be continuous random variables. Then the **joint probability density** function $f(y_1, y_2)$ satisfies $F(y_1, y_2) = \int_{-\infty}^{y_2} \int_{-\infty}^{y_1} f(t_1, t_2) dt_1 dt_2 \quad \forall y_1, y_2.$

The function $f(y_1, y_2)$ is a joint pdf if $f(y_1, y_2) \ge 0, \forall y_1, y_2$ and $\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(y_1, y_2) dy_1 dy_2 = 1.$

 $P(a_1 < Y_1 < b_1, a_2 < Y_2 < b_2) = \int_{a_2}^{b_2} \int_{a_1}^{b_1} f(y_1, y_2) dy_1 dy_2$

 $F(y_1, ..., y_n) = P(Y_1 \leq y_1, ..., Y_n \leq y_n)$. In the discrete case, the multivariate probability function is $p(y_1, ..., y_n) = P(Y_1 = y_1, ..., Y_n = y_n)$. In the continuous case, $f(y_1, ..., y_n)$ is a joint pdf if $F(y_1, ..., y_n) = \int_{-\infty}^{y_n} ... \int_{-\infty}^{y_1} f(t_1, ..., t_n) dt_1 \cdots dt_n$.

26) **Common Problem.** If $p(y_1, y_2)$ is given by a table, the marginal probability functions are found from the row sums and column sums and the conditional probability functions are found with the above formulas.

27) **COMMON FINAL PROBLEM.** Given the joint pdf $f(y_1, y_2) = kg(y_1, y_2)$ on its support, find k, find the marginal pdf's $f_{Y_1}(y_1)$ and $f_{Y_2}(y_2)$ and find the conditional pdf's $f_{Y_1|Y_2=y_2}(y_1|y_2)$ and $f_{Y_2|Y_1=y_1}(y_2|y_1)$.

Often using **symmetry** helps.

The support of the conditional pdf can depend on the 2nd variable. For example, the support of $f_{Y_1|Y_2=y_2}(y_1|y_2)$ could have the form $0 \le y_1 \le y_2$.

Double Integrals. If the region of integration Ω is bounded on top by the function $y_2 = \phi_T(y_1)$, on the bottom by the function $y_2 = \phi_B(y_1)$ and to the left and right by the lines $y_1 = a$ and $y_2 = b$ then $\int \int_{\Omega} f(y_1, y_2) dy_1 dy_2 = \int \int_{\Omega} f(y_1, y_2) dy_2 dy_2 =$

$$\int_{a}^{b} \left[\int_{\phi_{B}(y_{1})}^{\phi_{T}(y_{1})} f(y_{1}, y_{2}) dy_{2} \right] dy_{1}$$

Within the inner integral, treat y_2 as the variable, anything else, including y_1 , is treated as a constant.

If the region of integration Ω is bounded on the left by the function $y_1 = \psi_L(y_2)$, on the right by the function $y_1 = \psi_R(y_2)$ and to the top and bottom by the lines $y_2 = c$ and $y_2 = d$ then $\int \int_{\Omega} f(y_1, y_2) dy_1 dy_2 = \int \int_{\Omega} f(y_1, y_2) dy_2 dy_2 =$

$$\int_{c}^{d} \left[\int_{\psi_{L}(y_{2})}^{\psi_{R}(y_{2})} f(y_{1}, y_{2}) dy_{1} \right] dy_{2}.$$

Within the inner integral, treat y_1 as the variable, anything else, including y_2 , is treated as a constant.

The **support** of continuous random variables Y_1 and Y_2 is where $f(y_1, y_2) > 0$. The support (plus some points on the boundary of the support) is generally given by one to three inequalities such as $0 \le y_1 \le 1$, $0 \le y_2 \le 1$, and $0 \le y_1 \le y_2 \le 1$. For each variable, set the inequalities to equalities to get boundary lines. For example $0 \le y_1 \le y_2 \le 1$ yields 5 lines: $y_1 = 0, y_1 = 1, y_2 = 0, y_2 = 1$, and $y_2 = y_1$. Generally y_2 is on the vertical axis and y_1 is on the horizontal axis for pdf's.

To determine the **limits of integration**, examine the **dummy variable used in** the inner integral, say dy_1 . Then within the region of integration, draw a line parallel to the same (y_1) axis as the dummy variable. The limits of integration will be functions of the other variable (y_2) , never of the dummy variable (dy_1) .

If Y_1 and Y_2 are discrete RV's with joint probability function $p(y_1, y_2)$, then the **marginal pmf for** Y_1 is

$$p_{Y_1}(y_1) = \sum_{y_2} p(y_1, y_2)$$

where y_1 is held fixed. The marginal pmf for Y_2 is

$$p_{Y_2}(y_2) = \sum_{y_1} p(y_1, y_2)$$

where y_2 is held fixed. The **conditional pmf of** Y_1 **given** $Y_2 = y_2$ is

$$p_{Y_1|Y_2=y_2}(y_1|y_2) = \frac{p(y_1, y_2)}{p_{Y_2}(y_2)}.$$

The conditional pmf of Y_2 given $Y_1 = y_1$ is

$$p_{Y_2|Y_1=y_1}(y_2|y_1) = \frac{p(y_1, y_2)}{p_{Y_1}(y_1)}.$$

If Y_1 and Y_2 are continuous RV's with joint pdf $f(y_1, y_2)$, then the marginal probability density function for Y_1 is

$$f_{Y_1}(y_1) = \int_{-\infty}^{\infty} f(y_1, y_2) dy_2 = \int_{\phi_B(y_1)}^{\phi_T(y_1)} f(y_1, y_2) dy_2$$

where y_1 is held fixed (get the region of integration, draw a line parallel to the y_2 axis and use the functions $y_2 = \phi_B(y_1)$ and $y_2 = \phi_T(y_1)$ as the lower and upper limits of integration). The **marginal probability density function for** Y_2 is

$$f_{Y_2}(y_2) = \int_{-\infty}^{\infty} f(y_1, y_2) dy_1 = \int_{\psi_L(y_2)}^{\psi_R(y_2)} f(y_1, y_2) dy_1$$

where y_2 is held fixed (get the region of integration, draw a line parallel to the y_1 axis and use the functions $y_1 = \psi_L(y_2)$ and $y_1 = \psi_R(y_2)$ as the lower and upper limits of integration). The conditional probability density function of Y_1 given $Y_2 = y_2$ is

$$f_{Y_1|Y_2=y_2}(y_1|y_2) = \frac{f(y_1, y_2)}{f_{Y_2}(y_2)}$$

provided $f_{Y_2}(y_2) > 0$. The conditional probability density function of Y_2 given $Y_1 = y_1$ is

$$f_{Y_2|Y_1=y_1}(y_2|y_1) = \frac{f(y_1, y_2)}{f_{Y_1}(y_1)}$$

provided $f_{Y_1}(y_1) > 0$.

Random variables Y_1 and Y_2 are **independent** if any one of the following conditions holds.

i) $F(y_1, y_2) = F_{Y_1}(y_1)F_{Y_2}(y_2) \quad \forall y_1, y_2.$ ii) $p(y_1, y_2) = p_{Y_1}(y_1)p_{Y_2}(y_2) \quad \forall y_1, y_2.$ iii) $f(y_1, y_2) = f_{Y_1}(y_1)f_{Y_2}(y_2) \quad \forall y_1, y_2.$ Otherwise, Y_1 and Y_2 are dependent.

If $Y_1, Y_2, ..., Y_n$ are independent if $\forall y_1, y_2, ..., y_n$: i) $F(y_1, y_2, ..., y_n) = F_{Y_1}(y_1)F_{Y_2}(y_2)\cdots F_{Y_n}(y_n)$ ii) $p(y_1, y_2, ..., y_n) = p_{Y_1}(y_1)p_{Y_2}(y_2)\cdots p_{Y_n}(y_n)$ or

iii) $f(y_1, y_2, ..., y_n) = f_{Y_1}(y_1) f_{Y_2}(y_2) \cdots f_{Y_n}(y_n)$. Otherwise, the Y_i are dependent.

Two RV's Y_1 and Y_2 are dependent if their support is not a cross product of the support of Y_1 with the support of Y_2 . (A rectangular support is an important special case.) If the support is a cross product, another test must be used to determine whether Y_1 and Y_2 are independent or dependent.

For continuous Y_1 and Y_2 , then Y_1 and Y_2 are independent iff $f(y_1, y_2) = g(y_1)h(y_2)$ on **cross product support** where g is a positive function of y_1 alone and h is a positive function of y_2 alone. Or use $f(y_1, y_2) = g(y_1)h(y_2)$ for nonnegative h and g for all y_1 and y_2 (not just the cross product support).

To check whether discrete Y_1 and Y_2 (with rectangular support) are independent given a 2 by 2 table, find the row and column sums and check whether $p(y_1, y_2) \neq p_{Y_1}(y_1)p_{Y_2}(y_2)$ for some entry (y_1, y_2) . Then Y_1 and Y_2 are dependent. If $p(y_1, y_2) = p_{Y_1}(y_1)p_{Y_2}(y_2)$ for all table entries, then Y_1 and Y_2 are independent.

28) Common Problem. Determine whether Y_1 and Y_2 are independent or dependent.

Suppose that (Y_1, Y_2) are jointly continuous with joint pdf $f(y_1, y_2)$. Then the **expectation** $E[g(Y_1, Y_2)] = \int_{\chi_1} \int_{\chi_2} g(y_1, y_2) f(y_1, y_2) dy_2 dy_1 = \int_{\chi_2} \int_{\chi_1} g(y_1, y_2) f(y_1, y_2) dy_1 dy_2$ where χ_i are the limits of integration for dy_i .

In particular, $E(Y_1Y_2) = \int_{\chi_1} \int_{\chi_2} y_1y_2 f(y_1, y_2) dy_2 dy_1 = \int_{\chi_2} \int_{\chi_1} y_1y_2 f(y_1, y_2) dy_1 dy_2$

If g is a function of Y_i but not of Y_j , find the marginal for Y_i : If $g(Y_1)$ is a function of Y_1 but not of Y_2 , then $E[g(Y_1)] = \int_{\chi_1} \int_{\chi_2} g(y_1) f(y_1, y_2) dy_2 dy_1 = \int_{\chi_1} g(y_1) f_{Y_1}(y_1) dy_1$. (Usually finding the marginal is easier than doing the double integral.) Similarly, $E[g(Y_2)] = \int_{\chi_2} g(y_2) f_{Y_2}(y_2) dy_2$.

In particular, $E(Y_1) = \int_{\chi_1} y_1 f_{Y_1}(y_1) dy_1$, and $E(Y_2) = \int_{\chi_2} y_2 f_{Y_2}(y_2) dy_2$.

Suppose that (Y_1, Y_2) are jointly discrete with joint probability function $p(y_1, y_2)$. Then the **expectation** $E[g(Y_1, Y_2)] = \sum_{y_2} \sum_{y_1} g(y_1, y_2) p(y_1, y_2) = \sum_{y_1} \sum_{y_2} g(y_1, y_2) p(y_1, y_2)$.

In particular, $E[Y_1Y_2] = \sum_{y_2} \sum_{y_1} y_1y_2p(y_1, y_2).$

If g is a function of Y_i but not of Y_j , find the marginal for Y_i . If $g(Y_1)$ is a function of Y_1 but not of Y_2 , then $E[g(Y_1)] = \sum_{y_2} \sum_{y_1} g(y_1)p(y_1, y_2) = \sum_{y_1} g(y_1)p_{Y_1}(y_1)$. (Usually finding the marginal is easier than doing the double summation.) Similarly, $E[g(Y_2)] = \sum_{y_2} g(y_2)p_{Y_2}(y_2)$.

In particular, $E(Y_1) = \sum_{y_1} y_1 p_{Y_1}(y_1)$ and $E(Y_2) = \sum_{y_2} y_2 p_{Y_2}(y_2)$.

The covariance of Y_1 and Y_2 is $Cov(Y_1, Y_2) = E[(Y_1 - E(Y_1))(Y_2 - E(Y_2))].$

Short cut formula: $Cov(Y_1, Y_2) = E(Y_1Y_2) - E(Y_1)E(Y_2).$

Let Y_1 and Y_2 be independent random variables. If g is a function of Y_1 alone and h is a function of Y_2 alone, then $g(Y_1)$ and $h(Y_2)$ are independent random variables and $E[g(Y_1)h(Y_2)] = E[g(Y_1)]E[h(Y_2)]$ if the expectations exist. In particular, $E[Y_1Y_2] = E[Y_1]E[Y_2]$.

Know: Let Y_1 and Y_2 be independent random variables. Then $Cov(Y_1, Y_2) = 0$.

The converse is false: it is possible that $Cov(Y_1, Y_2) = 0$ but Y_1 and Y_2 are dependent.

29) COMMON FINAL PROBLEM. If $p(y_1, y_2)$ is given by a table, determine whether Y_1 and Y_2 are independent or dependent, find the marginal probability functions $p_{Y_1}(y_1)$ and $p_{Y_2}(y_2)$ and find the conditional probability function's $p_{Y_1|Y_2=y_2}(y_1|y_2)$ and $p_{Y_2|Y_1=y_1}(y_2|y_1)$. Also find $E(Y_1), E(Y_2), V(Y_1), V(Y_2), E(Y_1Y_2)$ and $Cov(Y_1, Y_2)$.

30) COMMON FINAL PROBLEM. Given the joint pdf $f(y_1, y_2) = kg(y_1, y_2)$ on its support, find k, find the marginal pdf's $f_{Y_1}(y_1)$ and $f_{Y_2}(y_2)$ and find the conditional pdf's $f_{Y_1|Y_2=y_2}(y_1|y_2)$ and $f_{Y_2|Y_1=y_1}(y_2|y_1)$. Also determine whether Y_1 and Y_2 are independent or dependent, and find $E(Y_1), E(Y_2), V(Y_1), V(Y_2), E(Y_1Y_2)$ and $Cov(Y_1, Y_2)$. If $Cov(Y_1, Y_2) \neq 0$, or if the support is not a cross product, then Y_1 and Y_2 are dependent. If $Cov(Y_1, Y_2) = 0$ and if the support is a cross product, you cannot tell whether Y_1 and Y_2 are dependent or not. In this case if you can show that $f(y_1, y_2) = g(y_1)h(y_2)$ on its cross product support or that $f(y_1, y_2) = f_{Y_1}(y_1)f_{Y_2}(y_2)$, then Y_1 and Y_2 are independent, otherwise Y_1 and Y_2 are dependent.

Often using **symmetry** helps.

 $E(c) = c, E[g_1(Y_1, Y_2) + \dots + g_k(Y_1, Y_2)] = E[g_1(Y_1, Y_2)] + \dots + E[g_k(Y_1, Y_2)].$ In particular, $E[aY_1 + bY_2] = aE[Y_1] + bE[Y_2].$

Know: Let a be any constant and let Y be a RV. Then E[aY] = aE[Y] and $V(aY) = a^2V(Y)$.

Let $Y_1, ..., Y_n$, and $X_1, ..., X_m$ be random variables. Let $U_1 = \sum_{i=1}^n a_i Y_i$ and $U_2 = \sum_{i=1}^m b_i X_i$ for constants $a_1, ..., a_n, b_1, ..., b_n$. Then $E(U_1) = \sum_{i=1}^n a_i E(Y_i)$,

31) **Common problem (Not in Text):** Find the pmf of Y = t(X) and the sample space \mathcal{Y} given the pmf $p_X(x)$ of X in a table. Step 1) Find y = t(x) for each value of x. Step 2) Collect x : t(x) = y, and sum the corresponding probabilities: $p_Y(y) = \sum_{x:t(x)=y} p_X(x)$, and table the result.

For example, if $Y = X^2$ and $p_X(-1) = 1/3$, $p_X(0) = 1/3$, and $p_X(1) = 1/3$, then $p_Y(0) = 1/3$ and $p_Y(1) = 2/3$.

32) Common problem (Not in Text), the method of transformations: Find the pdf of Y = t(X) and the sample space \mathcal{Y} given the pdf of X where t is increasing or decreasing:

$$f_Y(y) = f_X(t^{-1}(y)) \left| \frac{dt^{-1}(y)}{dy} \right|$$

for $y \in \mathcal{Y}$. To be useful, this formula should be simplified as much as possible. To find the support \mathcal{Y} of Y = t(X) if the support of X is $\mathcal{X} = [a, b]$, plug in t(x) and find the minimum and maximum value on [a, b]. A graph can help. If t is an increasing function, then $\mathcal{Y} = [t(a), t(b)]$. If t is an decreasing function, then $\mathcal{Y} = [t(b), t(a)]$.

Tips: a) The pdf of Y will often be that of a gamma RV. In particular, the pdf of Y is often the pdf of an exponential (λ) RV.

b) To find the inverse function $x = t^{-1}(y)$, solve the equation y = t(x) for x.

c) The log transformation is often used. Know how to sketch $\log(y)$ and e^y for y > 0. Recall that in this class, $\log(y)$ is the natural logarithm of y.

The method of distribution functions: Suppose that the distribution function $F_X(x)$ is known, Y = t(X), and both X and Y have pdfs.

a) If t is an increasing function then, $F_Y(y) = P(Y \le y) = P(t(X) \le y) = P(X \le t^{-1}(y)) = F_X(t^{-1}(y))$ for $y \in \mathcal{Y}$. b) If t is a decreasing function then, $F_Y(y) = P(Y \le y) = P(t(X) \le y) = P(t(X) \le y)$

 $P(X \ge t^{-1}(y)) = 1 - P(X < t^{-1}(y)) = 1 - F_X(t^{-1}(y))$ for $y \in \mathcal{Y}$.

c) The special case $Y = X^2$ is important. If the support of X is positive, use a). If the support of X is negative, use b). If the support of X is (-a, a) (where $a = \infty$ is allowed), then $F_Y(y) = P(Y \le y) =$

$$P(X^{2} \leq y) = P(-\sqrt{y} \leq X \leq \sqrt{y}) = \int_{-\sqrt{y}}^{\sqrt{y}} f_{X}(x) dx = F_{X}(\sqrt{y}) - F_{X}(-\sqrt{y}) \text{ for } 0 \leq y \leq a^{2}$$

and

$$f_Y(y) = \frac{1}{2\sqrt{y}} [f_X(\sqrt{y}) + f_X(-\sqrt{y})]$$

for $0 \le y \le a^2$.

33) Common Problem: Given two independent RV's X and Y, written $X \perp Y$ find $E(aX \pm bY) = aE(X) \pm bE(Y)$ and $V(aX \pm bY) = a^2V(X) + b^2V(Y)$.

34) The **moment generating function** (mgf) of a random variable Y is $m(t) = \phi(t) = E[e^{tY}]$. If Y is discrete, then $\phi(t) = \sum_{y} e^{ty} p(y)$, and if Y is continuous, then $\phi(t) = \int_{-\infty}^{\infty} e^{ty} f(y) dy$. The **kth moment** of Y is $E[Y^k]$. Given the mgf $\phi(t)$ exists for |t| < b for some constant b > 0, find the kth derivative $\phi^{(k)}(t)$. Then $E[Y^k] = \phi^{(k)}(0)$. In particular, $E[Y] = \phi'(0)$ and $E[Y^2] = \phi''(0)$.

Derivatives. The **product rule** is (f(y)g(y))' = f'(y)g(y) + f(y)g'(y). The **quotient rule** is $\left(\frac{n(y)}{d(y)}\right)' = \frac{d(y)n'(y) - n(y)d'(y)}{[d(y)]^2}$. Know how to find 2nd, 3rd, etc derivatives. The **chain rule** is [f(g(y))]' = [f'(g(y))][g'(y)]. Know the derivative of ln y $= \log(y)$ and e^y and know the chain rule with these functions. Know the derivative of y^k .

35) The **probability generating function** (pgf) of a random variable X is $P_X(z) = E[z^X]$. If X is discrete, then $P_X(z) = \sum_x z^x p(x)$, and if X is continuous, then $P_X(z) = \int_{-\infty}^{\infty} z^x f(x) dx$. If the pgf $P_X(z)$ exists for $z \in (1 - \epsilon, 1 + \epsilon)$ for some constant $\epsilon > 0$, find the kth derivative $P_X^{(k)}(z)$. Then $E[X(X-1)\cdots(X-k+1)] = P_X^{(k)}(1)$ where the product has k terms. In particular, $E[X] = P'_X(1)$ and $E[X^2 - X] = E(X^2) - E(X) = P''_X(1)$.

36) $\phi_X(t) = P_X(e^t)$ and $P_X(z) = \phi_X(\log(z))$.

37) Let $S_n = \sum_{i=1}^n X_i$ where the X_i are independent with mgf $\phi_{X_i}(t)$ and pgf $P_{X_i}(z)$. The mgf of S_n is $\phi_{S_n}(t) = \prod_{i=1}^n \phi_{X_i}(t) = \phi_{X_1}(t)\phi_{X_2}(t)\cdots\phi_{X_n}(t)$. The pgf of S_n is $P_{S_n}(z) = \prod_{i=1}^n P_{X_i}(z) = P_{X_1}(z)P_{X_2}(z)\cdots P_{X_n}(z)$.

Tips: a) in the product, anything that does not depend on the product index *i* is treated as a constant. b) $\exp(a) = e^a$ and $\log(y) = \ln(y) = \log_e(y)$ is the **natural logarithm**. c) $\prod_{i=1}^n a^{b\theta_i} = a^{\sum_{i=1}^n b\theta_i}$. In particular, $\prod_{i=1}^n \exp(b\theta_i) = \exp(\sum_{i=1}^n b\theta_i)$. d) $\sum_{i=1}^n b = nb$. e) $\prod_{i=1}^n a = a^n$.

X has a negative binomial distribution, $X \sim NB(k, p)$ if the pmf of X is

$$p(x) = \binom{x-1}{k-1} p^k (1-p)^{x-k} \text{ for } x = k, k+1, k+2, \dots \text{ where } 0$$

and k is a positive integer. Take $p(k) = p^k$. E(X) = k/p, $V(X) = k(1-p)/p^2$, $\phi(t) = \left[\frac{pe^t}{1-(1-p)e^t}\right]^k$. If $X \sim NB(k=1,p)$, then $X \sim geom(p)$. 38) Assume the X_i are independent.

a) If $X_i \sim N(\mu_i, \sigma_i^2)$, with support $(-\infty, \infty)$, then $\sum_{i=1}^n X_i \sim N(\sum_{i=1}^n \mu_i, \sum_{i=1}^n \sigma_i^2)$, and $\sum_{i=1}^{n} (a_i + b_i X_i) \sim N(\sum_{i=1}^{n} (a_i + b_i \mu_i), \sum_{i=1}^{n} b_i^2 \sigma_i^2)$. Here a_i and b_i are fixed constants. Thus if $X_1, ..., X_n$ are iid $N(\mu, \sigma^2)$, then $\overline{X} \sim N(\mu, \sigma^2/n)$.

b) If $X_i \sim G(\alpha_i, \lambda)$, then $\sum_{i=1}^n X_i \sim G(\sum_{i=1}^n \alpha_i, \lambda)$. Note that the X_i have the same λ , and if $\alpha_i \equiv \alpha$, then $\sum_{i=1}^n \alpha = n\alpha$. G stands for Gamma.

c) If
$$X_i \sim EXP(\lambda) \sim G(1,\lambda)$$
, then $\sum_{i=1}^n X_i \sim G(n,\theta)$.

d) If
$$X_i \sim \chi^2_{k_i} \sim G\left(\frac{k_i}{2}, 1/2\right)$$
, then $\sum_{i=1}^{n} X_i \sim \chi^2_{\sum_{i=1}^{n} k_i}$. If $k_i \equiv k$, then $\sum_{i=1}^{n} k = nk$.

e) If $X_i \sim \text{Poisson}(\lambda_i)$ then $\sum_{i=1}^n X_i \sim \text{Poisson}(\sum_{i=1}^n \lambda_i)$. Note that if $\lambda_i \equiv \lambda$, then $\sum_{i=1}^{n} \lambda = n\lambda.$

f) If $X_i \sim bin(k_i, p)$, then $\sum_{i=1}^n X_i \sim bin(\sum_{i=1}^n k_i, p)$. Note that the X_i have the same p, and if $k_i \equiv k$, then $\sum_{i=1}^n k = nk$.

g) Let NB stand for negative binomial. If $X_i \sim NB(k_i, p)$, then $\sum_{i=1}^n X_i \sim NB(\sum_{i=1}^n k_i, p)$ Note that the X_i have the same p, and if $k_i \equiv k$, then $\sum_{i=1}^n k = nk$. h) Let $X_i \sim geom(\beta) \sim NB(1, p)$. Then $\sum_{i=1}^n X_i \sim NB(n, p)$.

39) i) Given $\phi_X(t)$ or $P_X(t)$, use 34) and 35) to find E(X), $E(X^2)$, or $E(X^2) - E(X)$. Then find V(X) or $SD(X) = \sqrt{V(X)}$.

ii) Given a table for the pmr $p_X(x)$, find the mgf $\phi(t) = \phi_X(t) = \sum_x e^{tx} p_X(x)$, or the pgf $P_X(z) = \sum_x z^x p_X(x)$.

iii) Given ϕ_X or P_X as in ii), find the pmf $p_X(x)$.

iv) Given a brand name ϕ_X find the parameters of the brand name RV X.

40) Markov's inequality: If E(X) exists and $X \ge 0$ in that the support of $X \subseteq [0, \infty)$,

then for any constant a > 0, $P(X \ge a) \le \frac{E(X)}{a}$. 41) Chebyshev's inequality: If $E(X) = \mu$ and $V(X) = \sigma^2$, then for any constant $k > 0, P(|X - \mu| \ge k) \le \frac{\sigma^2}{k^2}.$ Also, $P(|X - \mu| \ge k\sigma) \le \frac{1}{k^2}$ so $P(|X - \mu| < k\sigma) \ge 1 - \frac{1}{k^2}.$ 42) Strong Law of Large Numbers (SLLN): Let X_1, X_2, \dots be iid with $E(X_i) = \mu.$ Then $X \to \mu$ as $n \to \infty$.

43) Central Limit Theorem (**CLT**): Let $Y_1, ..., Y_n$ be iid with $E(Y) = \mu$ and V(Y) = σ^2 . Let the sample mean $\overline{Y}_n = \frac{1}{n} \sum_{i=1}^n Y_i$. Then

$$\sqrt{n}(\overline{Y}_n - \mu) \xrightarrow{D} N(0, \sigma^2).$$

Hence

$$\sqrt{n}\left(\frac{\overline{Y}_n - \mu}{\sigma}\right) = \sqrt{n}\left(\frac{\sum_{i=1}^n Y_i - n\mu}{n\sigma}\right) = \left(\frac{\overline{Y}_n - \mu}{\sigma/\sqrt{n}}\right) = \left(\frac{\sum_{i=1}^n Y_i - n\mu}{\sqrt{n\sigma}}\right) \xrightarrow{D} N(0, 1).$$

The notation $X \sim Y$ means that the random variables X and Y have the same distribution. The notation $Y_n \xrightarrow{D} X$ means that for large n we can approximate the cdf of Y_n by the cdf of X. The distribution of X is the limiting distribution or asymptotic distribution of Y_n , and the limiting distribution does not depend on n. For the CLT, notice that

$$Z_n = \sqrt{n} \left(\frac{\overline{Y}_n - \mu}{\sigma} \right) = \left(\frac{\overline{Y}_n - \mu}{\sigma/\sqrt{n}} \right)$$

is the z–score of \overline{Y} and

$$Z_n = \left(\frac{\sum_{i=1}^n Y_i - n\mu}{\sqrt{n\sigma}}\right)$$

is the z-score of $\sum_{i=1}^{n} Y_i$. If $Z_n \xrightarrow{D} N(0, 1)$, then the notation $Z_n \approx N(0, 1)$, also written as $Z_n \sim AN(0, 1)$, means approximate the cdf of Z_n by the standard normal cdf. Similarly, the notation

$$\overline{Y}_n \approx N(\mu, \sigma^2/n),$$

also written as $\overline{Y}_n \sim AN(\mu, \sigma^2/n)$, means approximate the cdf of \overline{Y}_n as if $\overline{Y}_n \sim N(\mu, \sigma^2/n)$. Note that $U = U_n = \sum_{i=1}^n Y_i \approx N(n\mu, n\sigma^2)$ if the Y_i are iid. Note that the approximate distribution, unlike the limiting distribution, does depend on n. Use the limiting distribution or approximate distribution to find probabilities and percentiles.

44) **Common Problem.** Perform a forwards calculation for \overline{Y} using the normal table. In the story problem you will be told that $Y_1, ..., Y_n$ are iid with some mean μ and standard deviation σ (or variance σ^2). You will be told that "the CLT holds" or that the Y_i are "approximately normal". You will be asked to find the probability that the sample mean is greater than a or less than b or between a and b. That is, find $P(\overline{Y} > a)$ $P(\overline{Y} < b)$ or $P(a < \overline{Y} < b)$ (the strict inequalities (<, >) may be replaced with nonstrict inequalities (\leq, \geq)). Call a and b "ybar values."

Step 0) Find $\mu_{\overline{Y}} = \mu$ and $\sigma_{\overline{Y}} = \sigma/\sqrt{n}$.

Step 1) Draw the \overline{Y} picture with μ and the "ybar values" labeled.

Step 2) Find the z-score for each "ybar value", eg $z = \frac{a-\mu}{\sigma/\sqrt{n}}$.

Step 3) Draw a z-picture (sketch a N(0,1) curve and shade the appropriate area).

Step 4) Use the standard normal table to find the appropriate probability.

The CLT is what allows one to perform forwards calculations with Y. How large should n be to use the CLT? i) $n \ge 1$ for Y_i iid normal. ii) $n \ge 5$ for Y_i iid approximately normal. iii) If the Y_i are iid from a highly skewed distribution, do not use the normal approximation (forwards calculation) if $n \le 29$. iv) If n > 100, usually the CLT will hold in this class.

45) Common Problem (Not in Text). You are told that the Y_i are iid from a highly skewed distribution and that the sample size $n \leq 29$. You are asked to perform a forwards calculation such as $P(\overline{Y} > a)$ if possible. Solution: not possible n is too small for the CLT to apply.

46) Common Problem. Perform a forwards calculation for $\sum_{i=1}^{n} Y_i$ using the normal table if the Y_i are iid. Step 0) Find $\mu_{\sum Y_i} = n\mu$ and $\sigma_{\sum Y_i} = \sqrt{n\sigma}$.

Step 1) Draw the $\sum_{i=1}^{n} Y_i$ picture with $n\mu$ and the "sum values" labeled.

Step 2) Find the z-score for each "sum value", eg $z = \frac{a - n\mu}{\sqrt{n\sigma}}$.

Step 3) Draw a z-picture (sketch a N(0,1) curve and shade the appropriate area).

Step 4) Use the standard normal table to find the appropriate probability.

47) Think of $W \sim X|Y = y$. Then X|Y is a family of random variables. If E(X|Y = y) = m(y), then the random variable E(X|Y) = m(Y). Similarly if V(X|Y = y) = v(y), then the random variable $V(X|Y) = v(Y) = E(X^2|Y) - [E(X|Y)]^2$.

48) Assume all relevant expectations exist. Then iterated expectations or the conditional mean formula is $E(X) = E[E(X|Y)] = E_Y[E_{X|Y}(X|Y)]$. The conditional variance formula is V(X) = E[V(X|Y)] + V[E(X|Y)].

49) Let N be a counting RV with support $\subseteq \{0, 1, 2, ...\}$. Let $N \perp X_i$ where the X_i are independent, $E(X_i) = E(X)$ and $V(X_i) = V(X)$. Let $S_N = X_1 + X_2 + \cdots + X_N = \sum_{i=1}^N X_i$. Then $E(S_N) = E(N)E(X)$ and $V(S_N) = V(X)E(N) + [E(X)]^2V(N)$. If N = 0, then $S_N = 0$. $S = S_N$ is a compound RV and the distribution of N is the compounding distribution.

End probability, start stochastic processes.

50) A stochastic process $\{X(t) : t \in \tau\}$ is a collection of random variables where the set τ is often $[0, \infty)$. Often t is time and the random variable X(t) is the state of the process at time t.

51) A stochastic process $\{X(t) : t \in \{1, 2, ...\}\}$ is a white noise if $X_1, ..., X_t, ...$ are iid with $E(X_i) = 0$ and $V(X_i) = \sigma^2$.

52) A stochastic process $\{Y(t) : t \in \{1, 2, ...\}\}$ is a random walk if $Y(t) = Y_t = Y_{t-1} + e_t$ where the e_t are iid and $Y_0 = y_0$ is a constant. Then $Y_t = Y_{t-2} + e_{t-1} + e_t = Y_{t-j} + e_{t-j+1} + \cdots + e_t = y_0 + e_1 + e_2 + \cdots + e_t = y_0 + \sum_{i=1}^t e_i$ where $\sum_{i=1}^t e_i$ is known as a cumulative sum. If $E(e) = \delta$ and $V(e) = \sigma^2$, then $E(Y_t) = y_0 + t\delta$ and $V(Y_t) = t\sigma^2$.

Poisson Processes

53) A stochastic process $\{N(t) : t \ge 0\}$ is a counting process if N(t) counts the total number of events that occurred in time interval (0, t]. If $0 < t_1 < t_2$, then the random variable $N(t_2) - N(t_1)$ counts the number of events that occurred in interval $(t_1, t_2]$.

54) N(t) is said to possess independent increments if the number of events that occur in disjoint time intervals are independent. Hence if $0 < t_1 < t_2 < t_3 < \cdots < t_k$, then the RVs $N(t_1) - N(0), N(t_2) - N(t_1), \ldots, N(t_k) - N(t_{k-1})$ are independent.

55) N(t) is said to possess stationary increments if the distribution of events that occur in any time interval depends only on the length of the time interval.

56) A counting process $\{N(t) : t \ge 0\}$ is a Poisson process with rate λ for $\lambda > 0$ if i) N(0) = 0, ii) the process has independent increments, iii) the number of events in any interval of length t has a Poisson (λt) distribution with mean λt .

57) Hence the Poisson process N(t) has stationary increments, the number of events in (s, s+t] = the number of events in (s, s+t), and for all $t, s \ge 0$, the RV $D(t) = N(t+s) - N(s) \sim \text{Poisson } (\lambda t)$. In particular, $N(t) \sim \text{Poisson } (\lambda t)$. So $P(D(t) = n) = P(N(t+s) - N(s) = n) = P(N(t) = n) = \frac{e^{-\lambda t} (\lambda t)^n}{n!}$ for n = 0, 1, 2, ...

 $P(D(t) = n) = P(N(t+s) - N(s) = n) = P(N(t) = n) = -\frac{1}{n!} \text{ for } n = 0, 1, 2, \dots$ Also $E[D(t)] = V[D(t)] = E[N(t)] = V[N(t)] = \lambda t.$

58) Let X_1 be the waiting time until the 1st event, X_2 the waiting time from the 1st event until the 2nd event, ..., X_j the waiting time from the j-1th event until the *j*th event and so on. The X_i are called the waiting times or interarrival times. Let $S_n = \sum_{i=1}^n X_i$ the time of occurrence of the *n*th event = waiting time until the *n*th event. For a Poisson process with rate λ , the X_i are iid EXP(λ) with $E(X_i) = 1/\lambda$, and $S_n \sim \text{Gamma } (n, \lambda)$ with $E(S_n) = n/\lambda$ and $V(S_n) = n/\lambda^2$. Note that $S_n = S_{n-1} + X_n$ is

a random walk with $S_n = Y_n$, $Y_0 = y_0 = 0$ and the $e_i = X_i \sim EXP(\lambda)$.

59) If the waiting times = interarrival times are iid $\text{EXP}(\lambda)$, then N(t) is a Poisson

process with rate λ .

60) Suppose N(t) is a Poisson process with rate λ that counts events of k distinct types where $p_i = P(\text{ type } i \text{ event})$. If $N_i(t)$ counts type i events, then $N_i(t)$ is a Poisson process with rate $\lambda_i = \lambda p_i$, and the $N_i(t)$ are independent for i = 1, ..., k. Then $N(t) = \sum_{i=1}^k N_i(t)$ and $\lambda = \sum_{i=1}^k \lambda_i$ where $\sum_{i=1}^k p_i = 1$.

61) A counting process $\{N(t) : t \ge 0\}$ is a nonhomogeneous Poisson process with intensity function or rate function $\lambda(t)$, also called a nonstationary Poisson process, and has the following properties. i) N(0) = 0. ii) The process has independent increments.

iii) N(t) is a Poisson m(t) RV where $m(t) = \int_0^t \lambda(r) dr$, and N(t) counts the number of events that occurred in (0, t] (or (0, t)).

iv) Let $0 < t_1 < t_2$. The RV $N(t_2) - N(t_1) \sim \text{Poisson } (m(t_2) - m(t_1))$ where $m(t_2) - m(t_1) = \int_{t_1}^{t_2} \lambda(r) dr$ and $N(t_2) - N(t_1)$ counts the number of events that occurred in $(t_1, t_2]$ or (t_1, t_2) .

62) If N(t) is a Poisson process with rate λ and there are k distinct events where the probability $p_i(s)$ of the *i*th event at time s depends s, let $N_i(t)$ count type *i* events. Then $N_i(t)$ is a nonhomogeneous Poisson process with $\lambda_i(t) = \lambda \int_0^t p_i(s) ds$. Here $\sum_{i=1}^k p_i(s) = 1$ and the $N_i(t)$ are independent for i = 1, ..., k.

63) A stochastic process $\{X(t) : t \ge 0\}$ is a compound Poisson process if $X(t) = \sum_{i=1}^{N(t)} Y_i$ where $\{N(t) : t \ge 0\}$ is a Poisson process with rate λ and $\{Y_n : n \ge 0\}$ is a family of iid random variables independent of N(t). The parameters of the compound process are λ and $F_Y(y)$ where $E(Y_1)$ and $E(Y_1^2)$ are important. Then $E[X(t)] = \lambda t E(Y_1)$ and $V[X(t)] = \lambda t E(Y_1^2)$.

64) The compound Poisson process has independent and stationary increments. Fix r, t > 0. Then ${}_{t}X_{r} = X(r+t) - X(r)$ has the same distribution as the RV X(t). Hence $E({}_{t}X_{r}) = \lambda t E(Y_{1})$ and $V({}_{t}X_{r}) = \lambda t E(Y_{1}^{2})$.

65) Let $M_Y(t)$ be the moment generating function (mgf) of Y_1 . Then the mgf of the RV X(t) is

$$M_{X(t)}(r) = \exp(\lambda t [M_Y(r) - 1]).$$