

4) Fix A in \mathcal{F} . A PM 80

conditional probability of A given \mathcal{G} is $f = P[A|\mathcal{G}]$

that is i) measurable \mathcal{G} , integrable

$$\text{and ii) } \int_G P[A|\mathcal{G}] dP = E [P[A|\mathcal{G}] I_G] = P(A \cap G)$$

for any $G \in \mathcal{G}$.

5) i) $f = P[A|\mathcal{G}]$ is a random variable wrt \mathcal{G} .

ii) Let $v(G) = \int_G P[A|\mathcal{G}] dP = P(A \cap G)$, $G \in \mathcal{G}$.

$P(G) = 0 \Rightarrow v(G) = 0$. So the Radon-Nikodym

theorem can be applied to measures

v and P wrt (Ω, \mathcal{G}) . ($\mathcal{G} \subseteq \mathcal{F}$ so

P is defined on \mathcal{G} .) Hence $P[A|\mathcal{G}] \geq 0$.

$$0 \leq P[A|\mathcal{G}] \leq 1 \text{ w.p. 1.}$$

iii) There are many such RVS $P[A|\mathcal{G}]$

satisfying 4], but any two of them

are equal with prob 1. A specific

such RV is called a version of

the conditional probability. (unique up to sets of prob 0.)

iv) It is possible that $P(A) = 0$.

p452 ex) Suppose $A \in \mathcal{G}$. Then I_A is \mathcal{G} measurable

$$\text{and } \int_G I_A dP = \int I_A I_G dP = \int I_{A \cap G} dP =$$

$P(A \cap G)$. $\therefore I_A$ is a version of $P(A|\mathcal{G})$ if $A \in \mathcal{G}$.

p452 ex) $\mathcal{G} = \{\emptyset, \Omega\}$. The only \mathcal{G} measurable functions are constant functions. Let $f = P(A)$. Then $\int_{\emptyset} P(A) dP = 0 = P(A \cap \emptyset)$

$$\text{and } \int_{\Omega} P(A) dP = P(A \cap \Omega) = P(A).$$

$\therefore P(A)$ is a version of $P(A|\mathcal{G})$.

p453 ex) Let $A \perp \mathcal{G}$. and $f = P(A)$.

$$\int_G P(A) dP = P(A) \int I_G dP = P(A) P(G)$$

$$\stackrel{\uparrow}{=} P(A \cap G), \quad \therefore P(A) \text{ is a version of } P(A|\mathcal{G}).$$

§ 34 Conditional Expectation

PM 81

6) P466 (Let $E[X]$ exist on (Ω, \mathcal{F}, P) .)

The conditional expectation of X given \mathcal{G} is $f = E[X|\mathcal{G}]$ that is

i) measurable \mathcal{G} , integrable and ii)

$$\int_G f dP = \int_G E[X|\mathcal{G}] dP = E[E(X|\mathcal{G}) I_G] = E[X I_G] \\ = \int_G X dP \quad \text{for } G \in \mathcal{G}.$$

Here X is an integrable RV on (Ω, \mathcal{F}, P) .

7) Define ν on \mathcal{G} for nonnegative X by $\nu(G) = \int_G X dP$. Then $\nu \ll P$ and

by the Radon Nikodym theorem, there is a function f , measurable \mathcal{G} , such

$$\text{that } \nu(G) = \int_G f dP = \int_G X dP \quad \text{for } G \in \mathcal{G}.$$

If X is integrable, $f = E[X^+|\mathcal{G}] - E[X^-|\mathcal{G}]$

works. ↖ not necessarily non negative

8) There are many such RVs $E[X|\mathcal{G}]$.

Any one of them is a version of $E[X|\mathcal{G}]$ and any two versions are equal wpl.

9) If $X = I_A$, then $E[I_A | \mathcal{G}]$ is a version of $P[A | \mathcal{G}]$.

91.5

Proof) $\int_G E[I_A | \mathcal{G}] dP = \int_G I_A dP = \int I_A I_G dP$
 $= \int I_{A \cap G} dP = P(A \cap G) \quad \forall G \in \mathcal{G}.$

ex) If $\mathcal{G} = \mathcal{F}$, X is a version of $E(X | \mathcal{F})$

Since $\int_G X dP = \int_G X dP \quad \forall G \in \mathcal{F} = \mathcal{G}.$

ex) If $\mathcal{G} = \{\emptyset, \Omega\}$ ^{only} constants are measurable \mathcal{G} . Let $f = E(X)$.

$\int_{\emptyset} E(X) dP = E(X) P(\emptyset) = 0 = \int_{\emptyset} X dP$

$\int_{\Omega} E(X) dP = E(X) P(\Omega) = E(X) = \int_{\Omega} X dP$

$\therefore E(X)$ is a version of $E[X | \mathcal{G}]$.

eg: a constant
 \downarrow

10) If $\mathcal{G} \subseteq \mathcal{F}$, then often X is not measurable \mathcal{G} , and hence X is not a version of $E[X | \mathcal{G}]$. If X is measurable \mathcal{G} , then X is a version of $E[X | \mathcal{G}]$.

11) If X is measurable \mathcal{G} , then X acts like a constant given \mathcal{G} . (PM 82)

p469
12) Th: If X is measurable \mathcal{G} and Y and XY are integrable, then

$$E[XY | \mathcal{G}] = X E[Y | \mathcal{G}] \text{ wpl.}$$

That is, $X E[Y | \mathcal{G}]$ is a version of $E[XY | \mathcal{G}]$.

p468
13) Th: Suppose X, Y, X_n are integrable.

i) If $X = a$ wpl, then $E[X | \mathcal{G}] = a$ wpl.

ii) For constants a and b ,

$$E[(aX + bY) | \mathcal{G}] = a E[X | \mathcal{G}] + b E[Y | \mathcal{G}] \text{ wpl.}$$

iii) If $X \leq Y$ wpl, then $E[X | \mathcal{G}] \leq E[Y | \mathcal{G}]$ wpl.

iv) $|E[X | \mathcal{G}]| \leq E[|X| | \mathcal{G}]$ wpl. redundant

v) If $\lim_{n \rightarrow \infty} X_n = X$ wpl, $|X_n| \leq Y$, and Y is integrable,

then $\lim_{n \rightarrow \infty} E[X_n | \mathcal{G}] = E[X | \mathcal{G}]$ wpl.

some
Proofs i) a is measurable \mathcal{G}

82.5

$$\text{and } \int_G a dP = \int_G x dP = a P(G) \quad \forall G \in \mathcal{G}.$$

ii) $a E[X|Y] + b E[Y|Y]$ is measurable \mathcal{G}
and integrable. \therefore

$$\int_G (a E[X|Y] + b E[Y|Y]) dP =$$
$$a \int_G E[X|Y] dP + b \int_G E[Y|Y] dP =$$

$$a \int_G x dP + b \int_G y dP = \int_G (ax + by) dP \quad \forall G \in \mathcal{G}.$$

So $a E[X|Y] + b E[Y|Y]$ is a version
of $E[(ax + by)|Y]$.

iii) If $X \leq Y$ w.p.1, then

$$\int_G \underbrace{(E[Y|Y] - E[X|Y])}_{\text{measurable } \mathcal{G}} dP = \int_G (Y - X) dP \geq 0 \quad \forall G \in \mathcal{G}.$$

Let $g = E[Y|Y] - E[X|Y]$. Then $\{\omega: g(\omega) < 0\}$

$$= g^{-1}(-\infty, 0) = G_1 \in \mathcal{G}. \quad \int_{G_1} g dP \geq 0 \text{ and } g < 0 \text{ on } G_1$$

$$\Rightarrow P(G_1) = 0. \quad \therefore E[Y|Y] - E[X|Y] \geq 0 \text{ w.p.1.}$$

14) Th If X is integrable and σ fields

$\mathcal{A}_1 \subseteq \mathcal{A}_2 \subseteq \mathcal{F}$, then

$$\underbrace{E[E[X|\mathcal{A}_2]|\mathcal{A}_1]}_{\text{LHS}} = E[X|\mathcal{A}_1] \text{ w.p.1.}$$

Proof: $w = E[X|\mathcal{A}_2]$ is a RV wrt \mathcal{A}_2 , so

$E[w|\mathcal{A}_1] = \text{LHS}$ is measurable \mathcal{A}_1 .

Let $G \in \mathcal{A}_1$. Then $G \in \mathcal{A}_2$. Thus

$$\int_G E[E[X|\mathcal{A}_2]|\mathcal{A}_1] dP = \int_G w dP$$

$$= \int_G E[X|\mathcal{A}_2] dP \stackrel{G \in \mathcal{A}_2}{=} \int_G X dP \quad \forall G \in \mathcal{A}_1.$$

$\therefore E[E[X|\mathcal{A}_2]|\mathcal{A}_1]$ is a version

of $E[X|\mathcal{A}_1]$.

□

ex) suppose $X \perp \mathcal{A}$.

Then $E(X)$ is a version of $E[X|\mathcal{A}]$.

proof: $E(X)$ is a constant, so measurable. 83.5

$$\int_G E[X] dP = E[X] \int_G dP = E(X) P(G) \quad \forall G \in \mathcal{G}$$

while $\int_G X dP = \int X I_G dP = E[X I_G]$

$$\stackrel{(12)}{=} E[X] E(I_G) = E(X) P(G) \quad \forall G \in \mathcal{G}.$$

15) Intuitively, \mathcal{G} is information, so if \mathcal{G} is known, we know whether $G \in \mathcal{G}$ has occurred or not. So $E[X | \mathcal{G}]$ should be the "best guess" of X given information \mathcal{G} .

Earlier showed X is a version of $E[X | \mathcal{G}]$ if X is measurable \mathcal{G} .

16) Let $E[X | \mathcal{G}]$ be the class of all \mathcal{G} measurable RVS $E[X | \mathcal{G}]$.

Then $f \in E[X | \mathcal{G}]$ means f is a version of $E[X | \mathcal{G}]$.

17)* $\mathcal{G} \subseteq \mathcal{F}$ and X ~~is~~ measurable $\Rightarrow X^{-1}(B) \in \mathcal{G} \subseteq \mathcal{F} \Rightarrow X$ is ~~is~~ measurable. (good exam problem)

$\Rightarrow X^{-1}(B) \in \mathcal{F} \Rightarrow X$ is ~~is~~ measurable, converse is false