

$1-\delta$ is the nominal coverage, LS 61

and $1-\delta \leq \text{leninf}_n(1-\delta_n)$.

4) In a simulation let Y_{fi} be the i th random variable and Π_i the i th PI. $P(Y_{fi} \in \Pi_i) \sim \text{bin}(k; 1-\delta_n)$ $\approx \text{bin}(k, 1-\delta)$ where k is the number of runs in the simulation.

often want 90%, 95% and 99% PIs.

a) $K=5000$ simulated coverage $\in [0.94, 0.96]$

suggests actual coverage $1-\delta_n$ is close to the nominal coverage $1-\delta = 0.95$.

b) $K=100$ simulated coverage $\in [0.89, 1]$

suggests actual coverage $1-\delta_n$ is close to the nominal coverage $1-\delta = 0.95$

reasoning: $X_K \sim \text{bin}(K, 1-\delta) \stackrel{D}{=} \sum_{i=1}^K Y_i$

$Y_i \sim \text{bin}(1, 1-\delta)$, $V(Y_i) = (1-\delta)\delta$

(Let $0.9 \leq 1-\delta \leq 0.95$, but takes $\delta = .05$.)

61.5

$\frac{X_K}{K} = \bar{Y} = \hat{P}$ and want

$$\hat{P} \pm z_{1-\alpha} \sqrt{\frac{(1-\hat{P})\hat{P}}{K}} = \hat{P} \pm .06 \quad \text{for } k=100$$

$\approx .95$ for good 95% PI

$K=100$ want $z_{1-\alpha} 0.0218 = .06$

$$\text{or } z_{1-\alpha} = \frac{.06}{.0218} = 2.752.$$

$$K=5000 \quad \hat{P} \pm z_{1-\alpha} \sqrt{\frac{(1-\hat{P})\hat{P}}{K}} = \hat{P} \pm 0.01$$

$\approx .95$ for good 95% PI

$$\text{or } z_{1-\alpha} .00308 = .01$$

$$z_{1-\alpha} = \frac{.01}{.00308} = 3.244$$

That is pick $z_{1-\alpha}$ between 2 and 4

so that $z_{1-\alpha} \sqrt{\frac{(1-\hat{P})\hat{P}}{K}}$ is a simple percentage.

3) Rule of thumb; for $K=100$)
target sample 95% PIs

look at PIs with coverage ≥ 0.89 .

The PI with the shortest average length is best.

For $k=5000$, look at PIs with coverage ≥ 0.99 .

The PI with shortest length is best.

Note: can replace PIs with CIS, prediction regions, and confidence regions.

nominal 95% PI	a)	b)	c)	$k=100$
est cov .900	.86	.96		
len .400	.378	.383		
\curvearrowleft $\text{cov} \leq 0.89$				\uparrow best

6) For percentile based PIs

$$\{L_n, U_n\} = \left[\hat{Y}_{S_1}, \hat{Y}_{S_2} \right] \text{ with } S_2 - S_1 \geq 1-\delta$$

give large sample 100($+\delta$)% PIs.
see 7) and 9).

Need to use closed intervals
not open intervals.

ex) point mass at 0: $P(Y_E=0)=1$.
 $\bar{[0,0]}$ is a 100% PI and a large
sample 100(1- δ)% PI for $0 < \delta < 1$.
 $\underbrace{(0,0)}_{\text{empty set}} = \emptyset$ is a 0% PI.

7) Let Y_1, \dots, Y_n, Y_E be iid. Let
 $Y_{(1)} \leq \dots \leq Y_{(n)}$ be the order statistics
of the training data. Let $k_1 = \lceil \frac{n\delta}{2} \rceil$ and
 $k_2 = \lceil n(1-\frac{\delta}{2}) \rceil$ where $0 < \delta < 1$. The
large sample 100(1- δ)% percentile PI

for Y_E is $[Y_{(k_1)}, Y_{(k_2)}]$.

8) Let the shortest closed interval containing
at least c of the Y_1, \dots, Y_n be

$$\text{Shorth}(c) = [\bar{Y}_{(s)} \quad Y_{(s+c-1)}].$$

For Y_1, \dots, Y_n iid, and $k_n = \lceil n(1-s) \rceil$

Frey showed that the $\text{Shorth}(k_n)$ PI

has maximum undercoverage $\approx 1.12\sqrt{\frac{s}{n}}$

for large n s. The maximum undercoverage occurs for uniform (θ_1, θ_2) dists
(where the pop shorth is not unique).

Q3* Let Y_1, \dots, Y_n, Y_E be iid. The large sample $100(1-s)\%$ Shorth(c) PI

for Y_E is $[\bar{Y}_{(s)}, Y_{(s+c-1)}]$ where

$$c = \min(n, \lceil n [1-s + 1.12\sqrt{\frac{s}{n}}] \rceil).$$

correction factor

Idea: want 90% PI but max undercov = 5%
so use a 95% PI for the given N .

10) Let Y_1, \dots, Y_n, Y_E be iid.

Let $w_{(1)}, \dots, w_{(n)}$ be the order stats

of $w_i = \gamma^2$. Let $k_n = \lceil n(1-\delta) \rceil$. 63.5

Let $\hat{L}_n = -\hat{U}_n$ and $\hat{J}_n = \sqrt{w_{(k_n)}}$. Then

$[\hat{L}_n, \hat{U}_n]$ is a large sample $100(1-\delta)\%$ PI
for Y_E .

Note: a) $P(0 \leq w_E < \hat{U}_n^2) = P(-\sqrt{\hat{U}_n^2} \leq Y_E \leq \sqrt{\hat{U}_n^2})$

b) $P[\hat{L}_n \leq Y_E \leq \hat{U}_n]$ is eventually bounded below by $1-\delta$.

b) If $Y_E \geq 0$, use $[0, \hat{U}_n]$ as the PI.

113 By Chebyshev's ineq for $k > 1$,

$$P(\mu - k\sigma \leq Y \leq \mu + k\sigma) \geq 1 - \frac{1}{k^2}$$

Then $k=5$ gives $\geq 96\%$ asymptotic coverage.

123 Let $\bar{\mu} = \bar{Y}$ and $\bar{s} = \sqrt{s^2}$. Let Y_1, \dots, Y_n, Y_E be iid with $E(Y) = \mu$, $SD(Y) = \sqrt{V(Y)} = \sigma$.

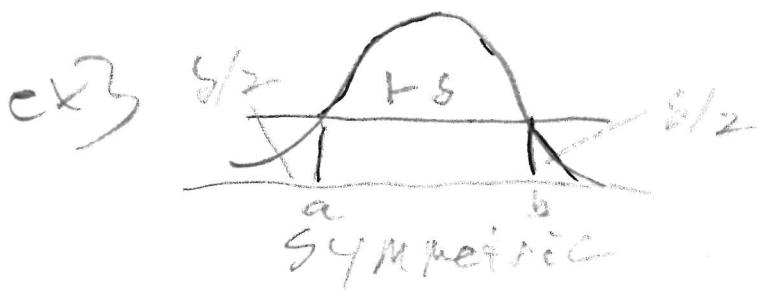
Let $1 - \frac{1}{k^2} \geq 1-\delta$. Let $\mu \pm k\sigma$ be continuity points of $F(y)$. Then $[\hat{L}_n, \hat{U}_n] = [\hat{\mu} - k\hat{\sigma}, \hat{\mu} + k\hat{\sigma}]$

is a large sample $100(1-\delta)\%$
Chebyshov PI.

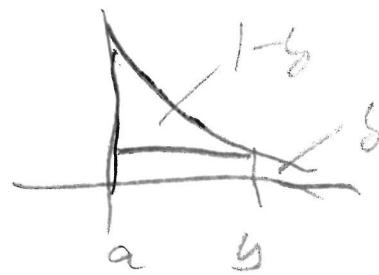
Note: This PI is usually too long if $k=5$.
 $k=1.96$ is often used for a 95% PI
 if the data are iid $N(\mu, \sigma^2)$. This PI is
 usually too short for a 95% PI if the
 data are not normal. (MLR and Time series)

End Exam 2 material

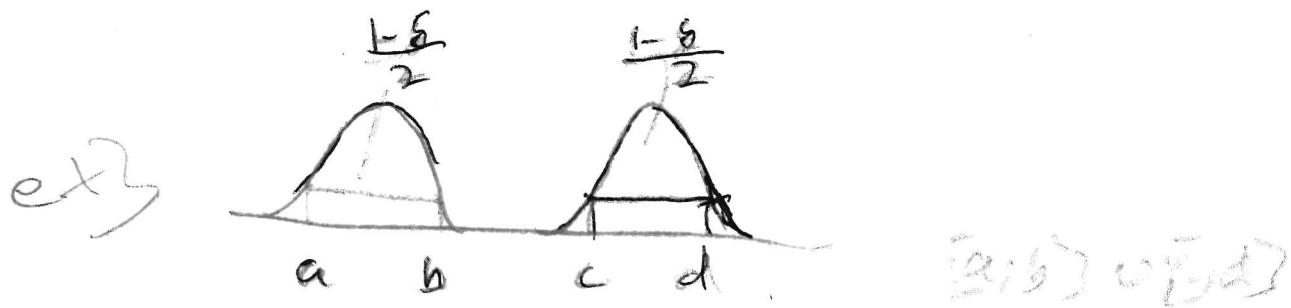
- (3) The $100(1-\delta)\%$ highest density
region is a union of k disjoint
 intervals such that the mass within
 the intervals $\geq 1-\delta$ and the sum
 of the k interval lengths is as small
 as possible. For a pdf move
 a horizontal line down from the
 top of the pdf. The line will intersect
 the pdf or boundaries of the pdf at
 $[a_1, b_1], \dots, [a_k, b_k]$ where $k \geq 1$. Stop
 moving the line when the areas under
 the pdf corresponding to the intervals = $1-\delta$.



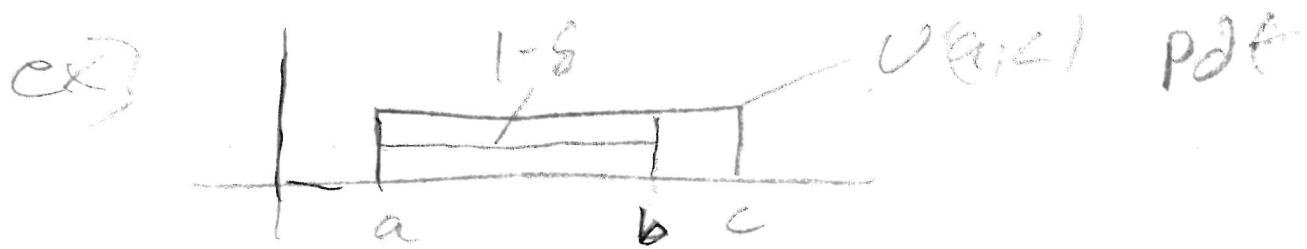
64.5



The two intervals $[a, b]$ are also the pop short.



[a, b] is the highest density region



[a, b] is a pop short and a highest density region

14) Large sample. Let the training data $\underline{x_1}, \underline{y_1}, \underline{x_n}$ and test data $\underline{x_f}$ be

A large sample $(00(1-\delta)\%$ Prediction region is a set A_n such that

$P(\underline{x}_t \in A_n)$ is eventually bounded below by 1-s as $n \rightarrow \infty$. A prediction region is asymptotically optimal if its volume converges to that of the highest density region (the minimum volume covering region) of the dist of \underline{x}_t .

15) Let the i th Mahalanobis distance

$$D_i = \sqrt{D_i^2} \quad \text{where}$$

$$D_i^2 = D_i^2(T, C) = (\underline{x}_i - T)^T C^{-1} (\underline{x}_i - T).$$

16) The sample mean $\bar{\underline{x}} = \frac{1}{n} \sum_{i=1}^n \underline{x}_i$ and the sample covariance matrix

$$S = \frac{1}{n-1} \sum_{i=1}^n (\underline{x}_i - \bar{\underline{x}})(\underline{x}_i - \bar{\underline{x}})^T.$$

17) Let $\underbrace{\underline{x}_1, \dots, \underline{x}_n}_{\text{training}}$, \underline{x}_t be iid,

a) If $X_i \stackrel{iid}{\sim} N_p(\mu, \Sigma)$, the large sample $100(1-\delta)\%$ MVN prediction region for \underline{x}_t is

$$\{\underline{z} : D_{\underline{z}}^2(\underline{x}, s) \leq D_{P_{1-\delta}}^2\}.$$

b) The large sample $100(1-\delta)\%$ nonparametric prediction region for \underline{x}_t is

$$\{\underline{z} : D_{\underline{z}}^2(\underline{x}, s) \leq D_{(v_n)}^2\}.$$

18) Let $g_n = \begin{cases} \min(1-s+0.05, 1-s+\frac{p}{n}) & s > 0.1 \\ \min(1-\frac{s}{2}, 1-s+10s\frac{p}{n}) & s \leq 0.1 \end{cases}$

If $1-s < 0.999$ and $g_n < 1-s+0.001$,

Set $g_n = (1-s)$. Let $D_{(v_n)}^2$ be the

$100 g_n$ th sample percentile of $D_i^2 = D_{X_i}^2$

for $i=1, \dots, n$.

So $D_{(v_n)}^2 \geq D_{(100(1-s)\bar{n})}^2$ and $D_{(v_n)}^2 \downarrow D_{(100(1-s)\bar{n})}^2$

strictly as $n \rightarrow \infty$.

19) The nonparametric prediction region starts to give good coverage for $N \geq 100$ and good volume for $N \geq 500$.

Like the CLT, there are always δ 's with nonsingular $\text{cov}(\underline{x}) = \underline{\Sigma}_x$ such that large N is needed.

20) If (\bar{T}, \bar{C}) is a consistent estimator

of (μ, d^2) for some constant $d > 0$,

then $D_x^2(\bar{T}, \bar{C}) = D^2(\bar{T}, \bar{C}) - \cdot \cdot \cdot$ is a

consistent estimator of $d^{-1} D_x^2(\mu, \Sigma)$.

Hence the sample percentiles of $D_i^2 = D_{X_i}^2$

estimate the pop percentiles of $d^{-1} D^2(\mu, \Sigma)$

at continuity points $D_{1-\delta}^2$ of the cdf

of $D^2 = D_x^2(\mu, \Sigma)$.

Proof) a) $D^2(\bar{T}, \bar{C}) = (\underline{x} - \bar{T})^T \bar{C}^{-1} (\underline{x} - \bar{T}) =$

$$(\underline{x} - \underline{\mu} + \bar{u} - \bar{T})^T \left[\bar{C}^{-1} - d^{-1} \bar{\Sigma}^{-1} + d^{-1} \bar{\Sigma}^{-1} \right] (\underline{x} - \underline{\mu} + \bar{u} - \bar{T})$$

$$= (\underline{x} - \underline{\mu})^T (d^{-1} \bar{\Sigma}^{-1}) (\underline{x} - \underline{\mu}) + (\underline{x} - \underline{\mu})^T \underbrace{(\bar{C}^{-1} - d^{-1} \bar{\Sigma}^{-1})}_{O_p(1)} (\underline{x} - \underline{\mu}) + \underbrace{(\bar{C}^{-1} - d^{-1} \bar{\Sigma}^{-1})}_{O_p(1)} \underbrace{(\bar{\Sigma}^{-1})}_{O_p(1)} (\underline{x} - \underline{\mu})$$

$4(\bar{x} - \underline{\mu})^T$ terms
 $2(\bar{u} - \bar{T})^T$ terms
 can get 5 terms

$$\begin{aligned}
 & + (\mu - \bar{\gamma})^T \tilde{C}^{-1} (\mu - \bar{\gamma}) + (\mu - \bar{\gamma})^T \tilde{C}^{-1} (\bar{x} - \bar{\mu}) + (\bar{x} - \bar{\mu})^T (\tilde{C}^{-1})^T (\mu - \bar{\gamma}) \\
 & \stackrel{\text{Op}(1)}{\sim} \text{Op}(1) \quad \text{Op}(1) \quad \text{Op}(1) \quad \text{Op}(1) \quad \text{Op}(1) \quad \text{Op}(1) \quad \text{Op}(1) \\
 & + (\bar{x} - \bar{\mu})^T (\tilde{C}^{-1} \tilde{d} \tilde{C}^{-1}) (\mu - \bar{\gamma}) = \tilde{d}^{-1} (\bar{x} - \bar{\mu})^T \tilde{C}^{-1} (\bar{x} - \bar{\mu}) + \text{Op}(1) \\
 & \stackrel{\text{Op}(1)}{\sim} \text{Op}(1) + \text{Op}(1) \\
 & = \tilde{d}^{-1} D_x^2(\mu, \tilde{C}) + \text{Op}(1).
 \end{aligned}$$

b) since C and \tilde{C} are nonsingular

$D_x^2(T, C)$ is a continuous function of (T, C) ,

$\therefore D_x^2(T, C) \xrightarrow{P} d D_x^2(\mu, \tilde{C})$.

2) a) $(\bar{x}, \bar{s}) \xrightarrow{P} (\mu, \tilde{C}) = (E(\bar{x}), \text{cov}(\bar{x}))$ with $d=1$.

b) If $X_i \sim N_p(\mu, \tilde{C})$, then $D_{X_i}^2(\bar{x}, \bar{s}) \xrightarrow{D} \chi_p^2$.

c) If $\Sigma \geq 0$, it is $(T - \bar{\mu}) \xrightarrow{D} N_p(0, \tilde{C})$; and if

$C \geq 0$ is a consistent estimator of Σ , then

$$n(T - \bar{\mu})^T C^{-1} (T - \bar{\mu}) \xrightarrow{D} \chi_p^2.$$

Och 5 confidence Regions and the Bootstrap

B Let $Y = (y_1, \dots, y_n)^T$ be the data. $[L_n, U_n] =$